NAME

 ${\rm CMSG_ALIGN,\,CMSG_SPACE,\,CMSG_NXTHDR,\,CMSG_FIRSTHDR\,-\,access\,ancillary\,\,data}$

SYNOPSIS

```
#include <sys/socket.h>
struct cmsghdr *CMSG_FIRSTHDR(struct msghdr *msgh);
struct cmsghdr *CMSG_NXTHDR(struct msghdr *msgh, struct cmsghdr *cmsg);
size_t CMSG_ALIGN(size_t length);
size_t CMSG_SPACE(size_t length);
size_t CMSG_LEN(size_t length);
unsigned char *CMSG_DATA(struct cmsghdr *cmsg);
struct cmsghdr {
    socklen_t cmsg_len; /* data byte count, including header */
    int cmsg_level; /* originating protocol */
    int cmsg_type; /* protocol-specific type */
    /* followed by unsigned char cmsg_data[]; */
};
```

DESCRIPTION

These macros are used to create and access control messages (also called ancillary data) that are not a part of the socket payload. This control information may include the interface the packet was received on, various rarely used header fields, an extended error description, a set of file descriptors or UNIX credentials. For instance, control messages can be used to send additional header fields such as IP options. Ancillary data is sent by calling sendmsg(2) and received by calling recvmsg(2). See their manual pages for more information.

Ancillary data is a sequence of $struct\ cmsghdr$ structures with appended data. This sequence should be accessed using only the macros described in this manual page and never directly. See the specific protocol man pages for the available control message types. The maximum ancillary buffer size allowed per socket can be set using $\frac{proc}{sys} \frac{proc}{core} \frac{proc}{optmem\ max}$; see $\frac{socket}{7}$.

CMSG_FIRSTHDR() returns a pointer to the first cmsghdr in the ancillary data buffer associated with the passed msghdr.

 $\mathbf{CMSG_NXTHDR}()$ returns the next valid $\mathit{cmsghdr}$ after the passed $\mathit{cmsghdr}$. It returns NULL when there isn't enough space left in the buffer.

CMSG_ALIGN(), given a length, returns it including the required alignment. This is a constant expression.

CMSG_SPACE() returns the number of bytes an ancillary element with payload of the passed data length occupies. This is a constant expression.

CMSG_DATA() returns a pointer to the data portion of a *cmsghdr*.

 $\mathbf{CMSG_LEN}()$ returns the value to store in the $\mathit{cmsg_len}$ member of the $\mathit{cmsghdr}$ structure, taking into account any necessary alignment. It takes the data length as an argument. This is a constant expression.

To create ancillary data, first initialize the $msg_controllen$ member of the msghdr with the length of the control message buffer. Use CMSG_FIRSTHDR() on the msghdr to get the first control message and CMSG_NXTHDR() to get all subsequent ones. In each control message, initialize $cmsg_len$ (with CMSG_LEN()), the other cmsghdr header fields, and the data portion using CMSG_DATA(). Finally, the $msg_controllen$ field of the msghdr should be set to the sum of the CMSG_SPACE() of the length of all control messages in the buffer. For more information on the msghdr, see recvmsg(2).

When the control message buffer is too short to store all messages, the MSG_CTRUNC flag is set in the msg_flags member of the msghdr.

CONFORMING TO

This ancillary data model conforms to the POSIX.1g draft, 4.4BSD-Lite, the IPv6 advanced API described in RFC 2292 and SUSv2. **CMSG ALIGN**() is a Linux extension.

NOTES

For portability, ancillary data should be accessed using only the macros described here. **CMSG ALIGN**() is a Linux extension and should not be used in portable programs.

In Linux, CMSG_LEN(), CMSG_DATA(), and CMSG_ALIGN() are constant expressions (assuming their argument is constant); this could be used to declare the size of global variables. This may not be portable, however.

EXAMPLE

This code looks for the IP TTL option in a received ancillary buffer:

```
struct msghdr msgh;
struct cmsghdr *cmsg;
int *ttlptr;
int received ttl;
/* Receive auxiliary data in msgh */
for (cmsg = CMSG\_FIRSTHDR(\&msgh); cmsg != NULL;
cmsg = CMSG NXTHDR(\&msgh,cmsg))  {
if (cmsg->cmsg level == IPPROTO IP
&& cmsg->cmsg type == IP TTL) {
ttlptr = (int *) CMSG DATA(cmsg);
received ttl = *ttlptr;
break;
}
if (cmsg == NULL) {
* Error: IP TTL not enabled or small buffer
* or I/O error.
*/
```

The code below passes an array of file descriptors over a UNIX domain socket using $\mathbf{SCM}_{\mathbf{RIGHTS}}$:

```
struct msghdr msg = \{0\};
struct cmsghdr *cmsg;
int myfds[NUM FD]; /* Contains the file descriptors to pass. */
char buf[CMSG SPACE(size of myfds)]; /* ancillary data buffer */
int *fdptr;
msg.msg control = buf;
msg.msg controllen = size of buf;
cmsg = CMSG FIRSTHDR(\&msg);
cmsg->cmsg level = SOL SOCKET;
cmsg->cmsg type = SCM RIGHTS;
cmsg->cmsg len = CMSG LEN(sizeof(int) * NUM FD);
/* Initialize the payload: */
fdptr = (int *) CMSG DATA(cmsg);
memcpy(fdptr, myfds, NUM_FD * sizeof(int));
/* Sum of the length of all control messages in the buffer: */
msg.msg controllen = cmsg->cmsg len;
```

SEE ALSO

recvmsg(2), sendmsg(2)

 $RFC\ 2292$

COLOPHON

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